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HTT33-01

Room:211

Time:May 2 09:15-09:30

#### Visual Surveillance of Natural Geography by means of UAV

HASEGAWA, Hitoshi<sup>1\*</sup>; ISOGAI, Tatsuhiro<sup>1</sup>; ONO, Isamu<sup>1</sup>

Unmanned aerial vehicle (UAV) systems can lead to major advances in physical geography. We have obtained a high-resolution digital aerial photographs using UAV (Unmanned Aerial Vehicle). UAV can make an automatic flight under the GPS control and take aerial photographs repeatedly with the same flight route. In this study, UAV was flying at 50 to 100m altitude. We have taken aerial photographs at coral reefs ,mangrove forests and the trench site of active fault. The high-resolution aerial photographs, a detailed classification map could be created, and it would also allow the extraction of dynamical topographic and vegetation development temporal changes.

Keywords: UAV, High-resolution digital aerial Pjotograh, Proximal Remote Sensing Method

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HTT33-02

Room:211

Time:May 2 09:30-09:45

#### The acquisition of geospatial information by small UAV

TANAKA, Kei<sup>1\*</sup>; KONDOH, Akihiko<sup>2</sup>

The recent advances of MEMS devices(GPS, gyro and acceleration sensor) has made possible low-cost and miniaturization. Thereby, multi-copter mounted with these sensors have appeared. That it requires a high level of technology and knowledge in the handling of RC traditional helicopter, beginners to steer is difficult. To enable even beginners to get easily geospatial information of high-resolution by multicopter.

In this study, we examined method of acquiring geospatial information(orthophoto, DSM, NDVI, and temperature distribution) by using small UAV.

Keywords: UAV (Unmanned Aerial Vehicle), SfM (Structure from Motion), DSM, orthophoto, NDVI, temperature distribution

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HTT33-03

Room:211

Time:May 2 09:45-10:00

#### UAV application and possibility for disaster prevention.

SAITOU, Osamu<sup>1\*</sup>; KUWAHARA, Yuji<sup>1</sup>

Videos of the tsunami taken from the airplane conveyed the horror of the recent great disaster which attacked the various places in eastern Japan, the Great East Japan Earthquake of 2011. Numerous engineers and researchers were shocked by the images. Moreover, many real-time movies and images of this disaster exist. Especially in the past several years, other disasters caused by extreme weather because of our changing climate, such as heavy typhoons, rain cataracts, flurries, and tornadoes, also cause widespread destruction. When these disasters or earthquakes occur, rapid situational assessment is crucially important, but it is difficult because transportation systems including roads and railways often shut down under those circumstances. Therefore, a monitoring system that provides information immediately when a disaster occurs is required. When a disaster occurs, monitoring from an airplane or satellite is effective but such systems are not easy to use. This study examines the possibility of disaster monitoring systems using uncrewed aerial vehicles (UAV).

Keywords: UAV, sensor network, sensor, disaster prevention

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HTT33-04

Room:211

Time:May 2 10:00-10:15

#### Proximity air measurement of the radiation by unmanned small helicopter

KAJIWARA, Koji<sup>1\*</sup>; HONDA, Yoshiaki<sup>1</sup>

The decontamination work of the radioactive material which dispersed in the accident of Fukushima nuclear power plant accompanying the Great East Japan Earthquake, is continuing to residential area, cultivated land, etc.

However, the still high dose is measured in the forest region.

It is a question whether safety can be guaranteed or not, even if it performs the roof of a house or building, and decontamination of only soil, when a forest is in living environment.

The radiation measuring instrument which enabled it to adjust the distance to the target for measurement with the winch attached to the small unmanned helicopter in this research is used, the dose of a tree crown from the position close to about 100m has been measured, and it was shown that field dose measurement in the forest is possible.

Moreover, even if it was the decontaminated place, it checked that a space dose in case it approaches and a forest exists changed with altitudes.

Keywords: UAV, Radiation Measurement, Forest Canopy

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HTT33-05

Room:211

Time:May 2 10:15-10:30

## Generating three-dimensional models by a software that unifies SfM and multiview stereo (MVS)

UCHIYAMA, Shoichiro1\*

In recent years, the software which unified Structure from Motion (SfM) and multi-view stereo (MVS) was developed. By this, construction of three-dimensional models and its Digital elevation models (DEMs) can be achieved with PC at easy and low cost. This paper shows a method for generating three-dimensional models by using with a SfM-MVS software and images captured by a handheld camera or an UAV's.

Keywords: structure from motion (SfM), three-dimensional model, digital surface model (DSM), unmanned aerial vehicle (UAV), geomorphometry, image acquisition for calculation

<sup>&</sup>lt;sup>1</sup>National Research Institute for Earth Science and Disaster Prevention (NIED)

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HTT33-06

Room:211

Time:May 2 10:30-10:45

#### Safety measures for multicopter aerial photo survey

INOUE, Hiroshi<sup>1\*</sup>; UCHIYAMA, Shoichiro<sup>1</sup>; SUZUKI, Hinako<sup>1</sup>

Low-altitude aerial photographing using multicopters, radio-controlled multi-rotor helicopters, became easy for everybody because of their recent technical advancement and price declines of the equipment. The technology will become popular rapidly as one of the methodologies of field surveys. Multicopters, however, can crash into the ground. We have experienced crash or near-crash accidents through our surveys and test flights in the past. The causes are sometimes a simple pilot error, loss of a propeller, unexpected strong wind, and out of battery, and are sometimes unclear, like GPS signal loss and barometer error, and their combinations. The crashes could have made serious injuries if the multicopters hit humans judging from the damage to the equipment we experienced.

The measures we take are careful pre-examination of the flight plan, making propeller guards, knowing battery capacity-flight time characteristics, monitoring battery voltage during the flight, regular maintenance of the batteries, pre-flight equipment checks, acceleration and compass calibrations, communication between the pilot and copilot, full utilization of autonomous flight, training of manual control for emergency, and following the safety check list.

Multicopter survey could cause problems to the society if accidents occur often as the result of popularization. If the usage becomes too strictly regulated, we may limit or even lose the large potential of applying the multicopter technology to our field survey. We therefore need to establish the safety measures to be obeyed, and share experiences of accidents for wider recognition of its potential danger, clarify individual causes, in order to strengthen the measures. Compliance to the aviation and wireless communication laws and regulations are indisputable. We also have to buy an insurance to compensate the possible damage caused by an accident.



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HTT33-P01

Room:Poster

Time:May 2 16:15-17:30

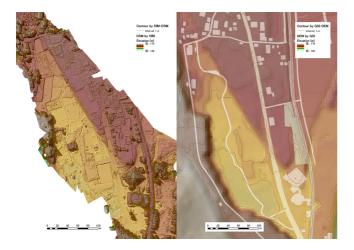
## Mapping active faults by using small unmanned aerial vehicle and structure from motion: a case study on Midori fault

UCHIYAMA, Shoichiro $^{1*}$ ; NAKATA, Takashi $^2$ ; INOUE, Hiroshi $^1$ ; KUMAHARA, Yasuhiro $^2$ ; SUGITA, Satoru $^3$ ; GOTO, Hideaki $^2$ ; IZUTSU, Jun $^3$ ; FUKUI, Hiromichi $^3$ ; SUZUKI, Hinako $^1$ ; TANIGUCHI, Kaoru $^4$ 

<sup>1</sup>National Research Institute for Earth Science and Disaster Prevention, <sup>2</sup>Hiroshima University, <sup>3</sup>Chubu University, <sup>4</sup>National Institute of Advanced Industrial Science and Technology

We photographed the geomorphometry of the Midori fault scarp formed by the 1891 Nobi earthquake in Motosu city, Gifu Prefecture (Japan) by using a multirotor radio control helicopter as a small unmanned aerial vehicle (sUAV), and we analysed these images. A digital surface model (DSM) of 0.09 m mesh and an orthophoto with a resolution of 0.03 m were generated from these images by PhotoScan software produced by structure from motion (SfM). A topographic map with 1 m interval contours and a cross-section profile were processed using a DSM produced by ArcGIS. We expect that the new technology will be applied to tectonic landform survey and geomorphology research. In addition, our results should help to ensure flight safety and compliance with the law.

Keywords: structure from motion (SfM), small unmanned aerial vehicle (sUAV), digital surface model (DSM), orthophoto, geomorphometry, midori fault scarp



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#### Generating an orthophoto from SfM calculation with the low-quality air photographs taken in the 1964 Niigata earthquake

SUZUKI, Hinako<sup>1\*</sup>; UCHIYAMA, Shoichiro<sup>1</sup>

This study shows that generating the orthophoto from low quality aerial photographs using structure from motion (SfM). National Research Institute for Earth Science and Disaster Prevention (NIED) is archiving a lot of old aerial photographs and its original roll films. However, some films are deteriorating. One of them is the 1964 Niigata earthquake's film. This deteriorated photographs were taken 50 years ago, nevertheless, the result of SfM calculating were sufficient quality and generated orthophoto with 0.2 m resolution. As a result, low quality aerial photographs are available to utilize for SfM.

Keywords: structure from motion (SfM), low quality aerial photograph, 1964 Niigata earthquake, ground control point (GCP), orthophoto



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HTT33-P03

Room:Poster

Time:May 2 16:15-17:30

#### Mapping of the fault scarp formed during the 2013 Bohol earthquake by small UAV

NAKATA, Takashi $^{1*}$ ; INOUE, Hiroshi $^{2}$ ; CAHULOGAN, Mabee $^{3}$ ; RIVERA, Danikko $^{3}$ ; LIM, Robjunelieaaa $^{3}$ ; POGAY, Cathy $^{3}$ 

A 5km-long surface fault rupture appeared during 2013 Bohol earthquake (M 7.1) in the Philippine. We took low-altitude air-photos of the ruptures using a small UAV, and made 3D images and contour maps by SfM software. This survey method is a low-cost, easy and effective method for mapping for quick respond field work for unexpected large earthquake damage especially in remote areas in under developing countries.

Keywords: UAV, SfM photogrammetry, earthquake fault, 2013 Bohol earthquake

<sup>&</sup>lt;sup>1</sup>Hiroshima University Professor Emeritus, <sup>2</sup>NIED, <sup>3</sup>PHIVOLCS

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HTT33-P04

Room:Poster

Time:May 2 16:15-17:30

# Multicopter Aerial Photo Survey of Building Damages by 2013 Bohol Eearthquake in the Philippines

 $INOUE, Hiroshi^{1*}; HANAZATO, Toshikazu^{2}; IMAI, Hiroshi^{1}; MELOSANTOS, Arnold^{3}; ALCONES, Ponzch^{3}; SORIANO, Karl vincent^{3}$ 

<sup>1</sup>National Research Institute for Earth Science and Disaster Prevention(NIED), <sup>2</sup>Mie University, <sup>3</sup>Philippine Institute for Volcanology and Seismology(PHIVOLCS)

We demonstrate the effectiveness of multicopter aerial photographing for recording earthquake damages of low to medium-rise buildings. M7.2 shallow inland earthquake occured on Bohol Island in the Philippines on October 15, 2013, which caused thousands of building damages and more than 200 casualties in the western part of the island. Post- earthquake surveys by PHIVOLCS showed the maximum earthquake intensity in Tagbilaran city near the epicentral area was VII in Philippines Eearthquake Intensity Scale, which is equivalent to VI in JMA intensity scale. We visited the island three weeks after the earthquake, to make the damage survey focusing on church buildings using a multicopter. We also carried out aerial photogrammetric survey of the surface rupture of the earthquake fault and the coastal uplift(Nakata et al., JpGU 2014) and the landslide damage of chocolate hill, a distinguishing morphology on the island.

A number of stone masonry churches founded in the 16th century in the Spanish colony times were damaged by the earthquake. The existing building of Baclayon Church, which was constructed in 1727 and known as the oldest church in the Philippines, lost the upper half of the bell tower and the whole front wall of the cathedral. Loboc Church and the adjoined museum in the Loboc city lost most of the side walls except their lower part. Maribojoc Church in the west and Clarin Church in the north of the island collapsed completely. Notable damages are also on non-structural masonry walls confined by RC columns and beams of public buildings, such as Sagbayan city hall and Tubigon city hall.

We used a small and easy-to-fly multicopter named DJI Phantom and a high-resolution and compact digital camera GoPro Hero3 Black Edition for the aerial photographing. We attached the camera facing obliquely down and manually controlled the copter in GPS stabilized mode. We used a FPV (First Person's View) system FatShark Telepoter V3 for watching the camera view. Photos were taken continuously in 2 seconds interval, while the copter was flying around the subjects. We limited the duration of each flight to five minutes and attached propeller guards to the rotors in order to reduce the possible dangers by crash as much as possible because people's activities in the areas around the churches were normal. We had no accident during the survey. We found that FPV is very useful in building damage survey because it can reduce the risk to crash to the building when taking photos, while it is difficult to know the distance from the copter to the subject in manual control from the ground.

The left figure shows the multicopter aerial photos of the damaged Baclayon Church. We can observe the fracture surfaces of the upper structure and its inside which are invisible from the ground. Aerial photographing using multicopter right after an earthquake is an efficient tool to easily get full picture of the damage even when approaching from the ground around a building is difficult. We then processed about 50 aerial photos using an SfM (Structure from Motion) software PhotoScan to reconstruct the 3-D model of the bell tower as shown in the right figure. The techniques enable modeling fractures of buildings and their analyses. The 3-D models are also valuable as digital architectural remains of disasters. Aerial photogrammetry using multicopter and SfM is easier than 3-D measurement using laser scanner. Creating a miniature of damaged building from the digital model using 3-D printer will also be useful for planning repairs and earthquake resistant design of buildings.

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HTT33-P05

Room:Poster

Time:May 2 16:15-17:30

#### Production of vegetation/landcover and dose rate maps by small helicopter and UAV

KONDOH, Akihiko<sup>1\*</sup>; HONDA, Yoshiaki<sup>1</sup>; KAJIWARA, Koji<sup>1</sup>; NORO, Naoki<sup>2</sup>; TAKARA, Yohei<sup>2</sup>; ANDO, Fuminori<sup>2</sup>; FUJIMORI, Takahiro<sup>2</sup>; NONAMI, Kenzo<sup>3</sup>; YAMAGUCHI, Hidetoshi<sup>4</sup>

<sup>1</sup>Center for Environmental Remote Sensing, Chiba University, <sup>2</sup>EBA JAPAN CO.,LTD., <sup>3</sup>Graduate School of Engineering, Chiba University, <sup>4</sup>SWR CO.,LTD.

The most essential and important information for restoration of the area contaminated by radioactive materials is dose rate and landcover map. The map should cover the SATOYAMA watershed with several hundreds to several kilometers scale, because the life in mountain village depend on water and material cycles in SATOYAMA watersheds and mode of deposition is strongly affected by vegetation type such as deciduous broad-leaved or evergreen coniferous forests. However, large scale maps on present vegetation and dose rate distribution are not available at present, so our team attempts to create vegetation/landcover map and dose rate distribution map by using UAV(Unmanned Areal Vehicle).

Manned helicopter (Robinson R44), radio controlled gasoline engined helicopter (YAMAHA/RMAX), and radio controlled electric multicopter (Minisurveyer MS-06L) are used as platform of dose rate measuring system. Dose rate is measured by radiation detector module (C12137-01, Hamamatsu Photonics) controlled by small laptop computer.

Hyperspectral camera (NH-7, Eba-Japan Co.,Ltd.) and video camera are installed on manned and unmanned helicopter to map precise vegetation and landcover map. In hyperspectral camera operation, both pushbroom and still images are taken. Motion video is captured to get still images, and mosaicked to ortho-areal photo.

Field campaign are carried out two times during August and November in 2013, and various photographing modes threedimensional dose rate mapping, and dose rate on various landcover such as forest canopy are attempted.

The campaign reveals the feasibility of low-cost, on-demand photographing and dose rate survey buy using UAV. Next subject is implementation to the actual scene. We plan to continue dose rate survey in Yamakiya district, Kawamata Town in Fukushima Prefecture.

Keywords: nuclear disaster, dose rate measurement, UAV, hyperspectral camera, Yamakiya District, FUKUSHIMA